

RALLY DOG SIGN SET

Incorporating FCI & KUSA Sign set – 01.10.2026

DEFINITION OF (A), (B), (C) & (D)

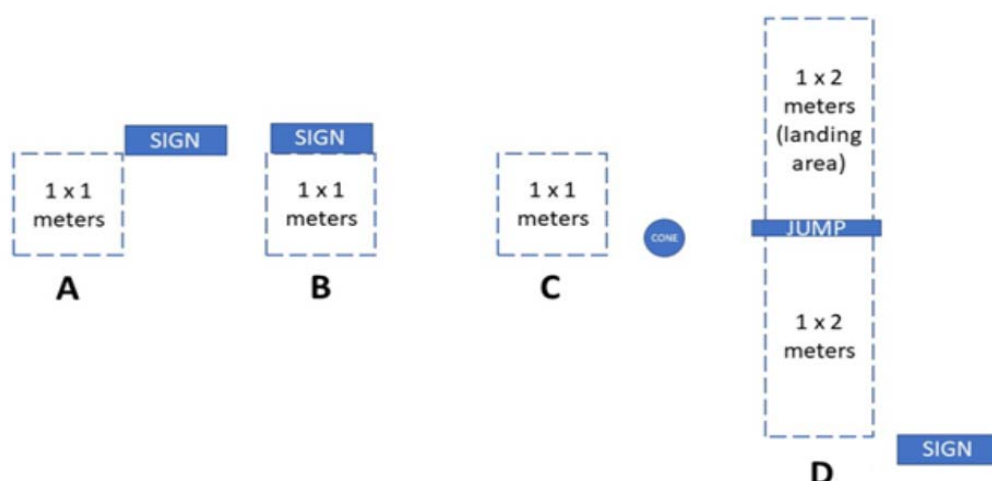
During performing an exercise, at least at one point a part of the team must be within the exercise area. Note, that the team is not allowed to go past the sign first and then start performing the exercise.

A: The exercise is performed on the left side of the sign when the direction of the course does not change (A). Exercises 417 and 418 begin according to (A), even though the direction is changed.

B: When the direction is changed or side steps are shown, the exercise is performed in front of the sign (B). The same counts for figure exercises 119, 120, 121, 122 and 221.

C: Recalls are done in front of the special recall signs (B), or next to the recall cone (C).

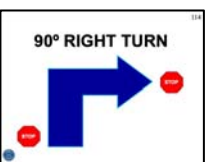
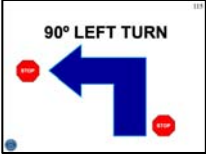
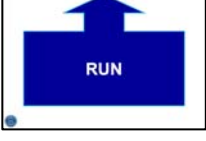
D: Exercises 222 and 320 begin at the earliest next to the sign. A landing area after the (last) jump is defined, where the dog must stay until the Handler catches up with the dog (D). The exercise area is 1 x 2 metres if no other instruction has been given. See picture below:

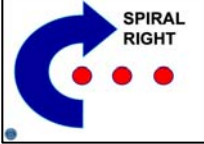
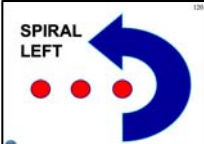
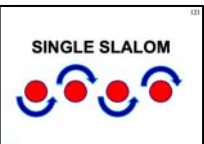
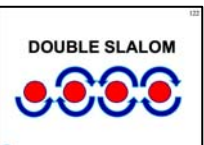
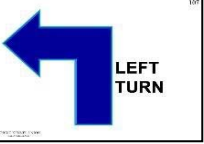


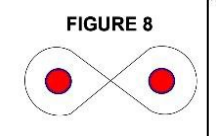
SIGN	DESCRIPTION
	START The dog sits at the Handler's left or right side. The Start Marker is in the position of the top right corner of the 1m exercise area. The Handler positions the dogs at the start of the 1m exercise area, the dog is in the Sit position. The Judge indicates that the Handler may start, and the dog and Handler move forward. Timing commences when either dog or Handler passes the Start Marker, whichever passes first.
	FINISH The course is finished when the team pass the Finish Marker. Timing is stopped when either dog or Handler passes the Finish Marker, whichever passes first. The team leaves the competition area at a normal pace.

LEVEL 1 signs

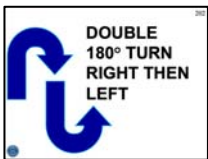
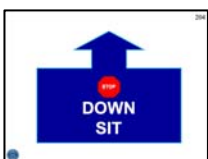
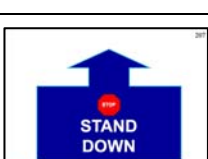
SIGN	DESCRIPTION
	101. DOWN (A) (Was KUSA 203) The Handler stops and the dog lies down directly beside the Handler. The dog stays down until the team moves forward.
	102. STOP, DOWN (A) The Handler stops and the dog sits beside the Handler. After that the dog is directed to a down position. The dog stays down until the team moves forward.
	103. STOP, WALK AROUND (A) (Was KUSA 104) The Handler stops and the dog sits beside the Handler. While the dog remains sitting, the Handler walks forward around the dog, back to the side of the dog, and makes a stop. The dog remains sitting until the team moves forward.
	104. STOP, DOWN, WALK AROUND (A) (Was KUSA 105) The Handler stops and the dog sits beside the Handler. After that the dog is directed to a down position. While the dog remains lying, the Handler walks forward around the dog, back to the side of the dog, and makes a stop. The dog stays down until the team moves forward.
	105. ABOUT TURN RIGHT (B) (Was KUSA 108) Together the team does a tight 180° turn to the right and moves in the opposite direction.
	106. ABOUT TURN LEFT (B) (Was KUSA 109) Together the team does a tight 180° turn to the left and moves in the opposite direction.
	107. LOOP RIGHT (B) (Was KUSA 110) Together the team does a tight turn to the right (Loop) crossing the original path. The angle of the turn must be between 180° and 270°.
	108. LOOP LEFT (B) (Was KUSA 111) Together the team does a tight turn to the left (Loop) crossing the original path. The angle of the turn must be between 180° and 270°.

	109. 270° RIGHT (B) (Was KUSA 112) Together the team does a tight 270° turn to the right. The new direction is 90° left to the original path.
	110. 270° LEFT (B) (Was KUSA 113) Together the team does a tight 270° turn to the left. The new direction is 90° right to the original path.
	111. 360° RIGHT (A) (Was KUSA 114) Together the team does a tight 360° turn to the right. The team keeps the original direction.
	112. 360° LEFT (A) (Was KUSA 115) Together the team does a tight 360° turn to the left. The team keeps the original direction.
	113. TURN AROUND DOG BEHIND (B) (Was KUSA 116) The Handler does an about turn to the side, where the dog is, while the dog turns to the side, where the Handler is. The dog is moving around behind the Handler and back to its initial heel position to continue moving with the Handler in the opposite direction.
	114. STOP, 90° RIGHT TURN, STOP (B) (Was KUSA 124) The Handler stops and the dog sits beside the Handler. The Handler does a 90° turn to the right on the spot and stops. The dog moves simultaneously with the Handler and resumes a sit when the Handler stops. The dog remains sitting until the team moves forward.
	115. STOP, 90° LEFT TURN, STOP (B) (Was KUSA 125) The Handler stops and the dog sits beside the Handler. The Handler does a 90° turn to the left on the spot and stops. The dog moves simultaneously with the Handler and resumes a sit when the Handler stops. The dog remains sitting until the team moves forward.
	116. SLOW PACE (A) (Was KUSA 126) The team must slow down noticeably. The slow pace must be kept, until a sign shows a new pace, or the team has reached the Finish Marker.
	117. RUN (A) (Was KUSA 127) The team must speed up noticeably. The fast pace must be kept, until a sign shows a new pace, or the team has reached the Finish Marker.

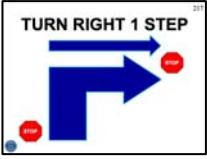
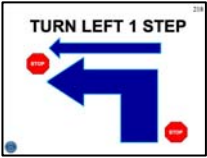
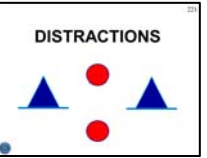
	118. NORMAL PACE (A) (Was KUSA 128) The team returns to normal pace.
	119. SPIRAL RIGHT (B) (Was KUSA 129) Three cones are placed in a straight line with spaces between them of 1,5 to 2 m. The team first rounds three cones on the left side, then the nearest two, then the first one.
	120. SPIRAL LEFT (B) (Was KUSA 130) Three cones are placed in a straight line with spaces between them of 1,5 to 2 m. The team first rounds three cones on the right side, then the nearest two, then the first one.
	121. SINGLE SLALOM (B) (Was KUSA 131) Four cones are placed in a straight line with spaces between them of 1,5 to 2 m. The team must enter the exercise with the first cone on its left and weaves through the four cones.
	122. DOUBLE SLALOM (B) (Was KUSA 132) Four cones are placed in a straight line with spaces between them of 1,5 to 2 m. The team must enter the exercise with the first cone on its left, weaves through the four cones, rounds the end cone and weaves back.
	123. STOP (A) (Was KUSA 101) The Handler stops, and the dog sits beside the Handler. When completed, the team moves forward.
	124. RIGHT TURN (B) (Was KUSA 106) 90° tight turn to the right.
	125. LEFT TURN (B) (Was KUSA 107) 90° tight turn to the left.
	126. CALL FRONT- STOP - RIGHT TO LEFT (A) (Was KUSA 117) The Handler stops, and the dog is directed to sit in front of the Handler. After that the dog is directed to the Handler's right and behind the Handler to the left side. The team then move forward without stopping.
	127. CALL FRONT – STOP - LEFT TO LEFT (A) (Was KUSA 118) The Handler stops, and the dog is directed to sit in front of the Handler. After that the dog is directed to the Handler's left side. The team then move forward without stopping.

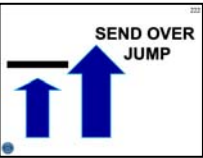
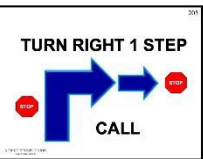
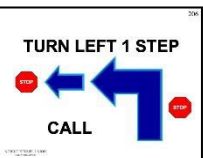
	128. CALL FRONT – STOP - RIGHT TO LEFT – STOP (A) (Was KUSA 119) The Handler stops, and the dog is directed to sit in front of the Handler. After that the dog is directed to the Handler's right and behind the Handler to the left side. The dog sits before the team move forward.
	129. CALL FRONT – STOP - LEFT TO LEFT – STOP (A) (Was KUSA 120) The Handler stops, and the dog is directed to sit in front of the Handler. After that the dog is directed to the Handler's left side. The dog sits before the team move forward.
	130. STOP – 1 STEP, STOP – 2 STEPS, STOP – 3 STEPS, STOP (A) (Was KUSA 123) The Handler stops, and the dog sits beside the Handler. The Handler takes one step forward, stops, two steps forward, stops, three steps forward, and stops. The dog moves with the Handler and resumes a sit every time the Handler stops.
	131. FIGURE 8 (B) (Was KUSA 133) Two cones are placed 2,5 – 3 metres apart. The team must enter the exercise as decided by the Judge. The team performs a complete figure 8 around the cones, crossing the centre line three times.

LEVEL 2 signs

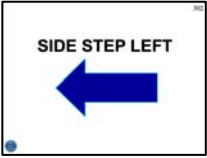
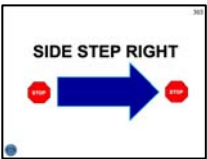
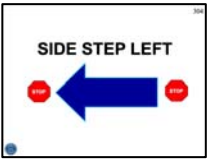
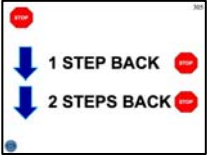
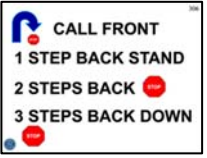
SIGN	DESCRIPTION
	201. 2 x TURN AROUND DOG BEHIND (A) The Handler does an about turn to the side, where the dog is, while the dog turns to the side, where the Handler is. The dog is moving around behind the Handler and back to its initial heel position to continue moving with the Handler in the opposite direction. After 1 to 2 m the Handler does again an about turn to the side, where the dog is, while the dog turns again to the side, where the Handler is. The dog is moving again around behind the Handlers back to its initial heel position to continue moving with the Handler in the same direction as before the exercise.
	202. DOUBLE 180° TURN, RIGHT THEN LEFT (A) Together the team does a tight 180° turn to the right and moves in the opposite direction. After 1 to 2 m the team does together a tight 180° turn to the left and moves in the same direction as before the exercise.
	203. DOUBLE 180° TURN, LEFT THEN RIGHT (A) Together the team does a tight 180° turn to the left and moves in the opposite direction. After 1 to 2 m the team does together a tight 180° turn to the right and moves in the same direction as before the exercise.
	204. STOP, DOWN, SIT (A) (Was KUSA 203) The Handler stops and the dog sits beside the Handler. After that the dog is directed to a down position, followed by a sit position. The dog remains sitting until the team moves forward.
	205. STOP, STAND (A) (Was KUSA 202) The Handler stops and the dog sits beside the Handler. After that the dog is directed to a stand position. The dog remains standing until the team moves forward.
	206. STOP, STAND, SIT (A) (Was KUSA 302) The Handler stops and the dog sits beside the Handler. After that the dog is directed to a stand position, followed by a sit position. The dog remains sitting until the team moves forward.
	207. STOP, STAND, DOWN (A) (Was KUSA 301) The Handler stops and the dog sits beside the Handler. After that the dog is directed to a stand position, followed by a down position. The dog stays down until the team moves forward.

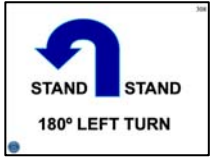
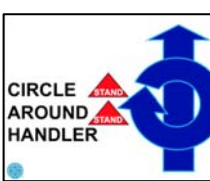
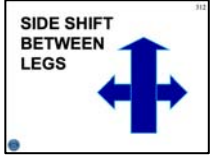
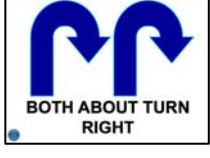
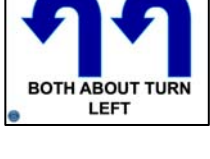
	208. STOP, STAND, WALK AROUND (A) (Was KUSA 303) The Handler stops and the dog sits beside the Handler. After that the dog is directed to a stand position. While the dog remains standing, the Handler walks forward around the dog, back to the side of the dog, and makes a stop. The dog remains standing until the team moves forward.
	209. STOP, CALL FRONT STOP, RIGHT TO LEFT, STOP (A) (Was KUSA 121) The Handler stops and the dog sits beside the Handler. After that the dog is directed to sit in front of the Handler. The dog is then directed to move to the Handler's right and behind the Handler to the left side. The dog sits before the team moves forward. Return to left handling.
	210. STOP, CALL FRONT STOP, LEFT TO LEFT, STOP (A) (Was KUSA 122) The Handler stops and the dog sits beside the Handler. After that the dog is directed to sit in front of the Handler. The dog is then directed to move directly to the Handler's left side. The dog sits before the team moves forward. Return to left handling.
	211. STOP, 1 STEP FORWARD, 90° RIGHT TURN 1 STEP, CALL, STOP (B) The Handler stops and the dog sits beside the Handler. The dog remains sitting while the Handler takes one step forward, stops and thereafter does a 90° turn to the right, again takes one step in the new direction, and again stops. The step to the right can either be taken directly or the Handler can turn on the spot and then take the step. After that the dog is called to sit at the Handler's side (no change of the heeling side). The dog remains sitting until the team moves forward.
	212. STOP, 1 STEP FORWARD, 90° LEFT TURN 1 STEP, CALL, STOP (B) The Handler stops and the dog sits beside the Handler. The dog remains sitting while the Handler takes one step forward, stops and thereafter does a 90° turn to the left, again takes one step in the new direction, and again stops. The step to the left can either be taken directly or the Handler can turn on the spot and then take the step. After that the dog is called to sit at the Handler's side (no change of the heeling side). The dog remains sitting until the team moves forward.
	213. STOP, 180° RIGHT TURN, FORWARD (B) (Was KUSA 207) The Handler stops and the dog sits beside the Handler. Together the team does a tight 180° turn to the right on the spot and continues forward, in the opposite direction.
	214. STOP, 180° LEFT TURN, FORWARD (B) (Was KUSA 209) The Handler stops and the dog sits beside the Handler. Together the team does a tight 180° turn to the left on the spot and continues forward, in the opposite direction.

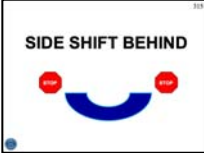
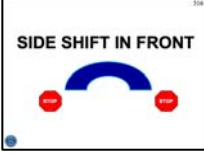
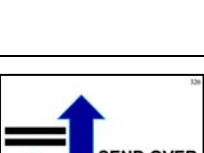
	215. STOP, 180° RIGHT TURN, STOP (B) (Was KUSA 208) The Handler stops and the dog sits beside the Handler. Together the team does a tight 180° turn to the right on the spot, stops and the dog is directed to a sit position. The dog remains sitting until the team moves forward.
	216. STOP, 180° LEFT TURN, STOP (B) (Was KUSA 210) The Handler stops and the dog sits beside the Handler. Together the team does a tight 180° turn to the left on the spot, stops and the dog is directed to a sit position. The dog remains sitting until the team moves forward.
	217. STOP, 90° RIGHT TURN 1 STEP, STOP (B) (Was KUSA 211) The Handler stops and the dog sits beside the Handler. The Handler does a 90° turn to the right, takes one step, and stops. The step can either be taken directly or the Handler can turn on the spot and then take the step. The dog moves simultaneously with the Handler and resumes a sit when the Handler stops. The dog remains sitting until the team moves forward.
	218. STOP, 90° LEFT TURN 1 STEP, STOP (B) (Was KUSA 212) The Handler stops and the dog sits beside the Handler. The Handler does a 90° turn to the left, takes one step, and stops. The step can either be taken directly or the Handler can turn on the spot and then take the step. The dog moves simultaneously with the Handler and resumes a sit when the Handler stops. The dog remains sitting until the team moves forward.
	219. STOP, 1 STEP STAND, 2 STEPS STOP, 3 STEPS DOWN (A) (Was KUSA 310) The Handler stops and the dog sits beside the Handler. After that the Handler takes one step forward and stops. The dog moves simultaneously with the Handler and assumes a stand when the Handler stops. The Handler then takes two steps forward and stops. The dog moves simultaneously with the Handler and assumes a sit when the Handler stops. Thereafter the Handler takes three steps forward and stops. The dog moves simultaneously with the Handler and assumes a down when the Handler stops. The dog stays down until the team moves forward.
	220. SPIN (A) (Was KUSA 312) While the team is moving, the dog spins a circle forward, alongside and in the direction away from the Handler.
	221. DISTRACTIONS (B) Two cones are placed 2,5 to 3 m apart (blue triangles). The distance between the other two markings (distractions) is 1,5 to 2 m (red dots). The team must enter the exercise as decided by the Judge and performs a complete figure 8 around the cones, crossing the line between the distractions 3 times. Toys, treats or both may be used as distractions. Treats are to be in sealed container with holes pierced for the scent to be available (the dog must not be able to get access to the treats/food).

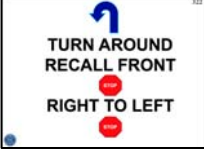
	222. SEND OVER JUMP (D) (Was KUSA 214) The dog is sent over the jump at the earliest next to the sign that is two (2) metres before the jump. At the same time the Handler continues alongside the jump. The Handler may increase the pace to catch up with the dog.
	223. STOP – RUN FROM SIT (A) (Was KUSA 204) The Handler stops, and the dog sits beside the Handler. The team runs forward until another sign instructs them to change pace.
	224. STOP – TURN RIGHT 1 STEP – CALL – STOP (A) (Was KUSA 205) The Handler stops, and the dog sits beside the Handler. The dog remains sitting while the Handler takes one step to the right and stops. The step can either be taken directly or the Handler can turn on the spot and take the step. The dog is then recalled to sit at the Handler's side.
	225. STOP – TURN LEFT 1 STEP – CALL – STOP (A) (Was KUSA 206) The Handler stops, and the dog sits. The dog remains sitting while the Handler takes one step to the left and stops. The step can either be taken directly or the Handler can turn on the spot and take the step. The dog is then recalled to sit at the Handler's side.
	226. CALL FRONT STOP – 1 STEP BACK STOP – 2 STEPS BACK STOP – 3 STEPS BACK STOP (A) (Was KUSA 213) The Handler stops, and the dog is directed to sit in front of the Handler. The Handler takes one step backward, stops, two steps backward, stops, three steps backward and stops. The dog moves with the Handler and resumes a sit in front of the Handler when the Handler stops. The dog is then directed to the Handlers left side and the team continues forward.

LEVEL 3 signs

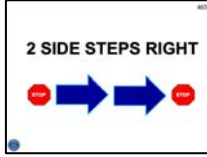
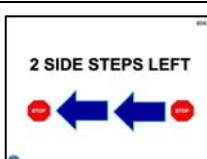
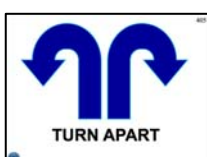
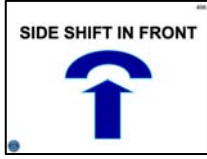
SIGN	DESCRIPTION
	301. SIDESTEP RIGHT (B) (Was KUSA 401) While moving, the Handler takes one step to the right and the dog follows simultaneously aligned with and parallel to the Handler. The team continues to the right side of the sign.
	302. SIDESTEP LEFT (B) (Was KUSA 402) While moving, the Handler takes one step to the left and the dog follows simultaneously aligned with and parallel to the Handler.
	303. STOP, SIDESTEP RIGHT, STOP (B) (Was KUSA 306) The Handler stops and the dog sits beside the Handler. The Handler takes one step to the right and stops. The dog moves simultaneously aligned with and parallel to the Handler and resumes a sit when the Handler stops. The dog remains sitting until the team moves forward. The team continues to the right side of the sign.
	304. STOP, SIDESTEP LEFT, STOP (B) (Was KUSA 307) The Handler stops and the dog sits beside the Handler. The Handler takes one step to the left and stops. The dog moves simultaneously aligned with and parallel to the Handler and resumes a sit when the Handler stops. The dog remains sitting until the team moves forward.
	305. STOP, 1 STEP BACK STOP, 2 STEPS BACK, STOP (A) (Was KUSA 411) The Handler stops and the dog sits beside the Handler. After that the Handler takes one step backwards and stops. The dog moves simultaneously and aligned with and parallel to the Handler and resumes a sit when the Handler stops. Then the Handler takes two steps backwards and stops. The dog moves simultaneously with and parallel to the Handler and resumes a sit when the Handler stops. The dog remains sitting until the team moves forward.
	306. CALL FRONT STOP, 1 STEP BACK STAND, 2 STEPS BACK STOP, 3 STEPS BACK DOWN (A) The Handler stops and the dog is directed to sit in front of the Handler. After that the Handler takes one step backwards and stops. The dog moves simultaneously with the Handler and assumes a stand in front of the Handler when the Handler stops. The Handler then takes two steps backwards and stops. The dog moves simultaneously with the Handler and assumes a sit in front of the Handler when the Handler stops. Thereafter the Handler takes three steps backwards and stops. The dog moves simultaneously with the Handler and assumes a down in front of the Handler when the Handler stops. The dog is then directed to the Handler's left side and the dog sits beside the Handler. The dog remains sitting until the team moves forward. Return to left handling.

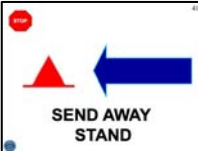
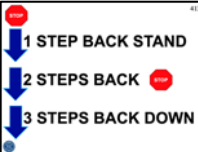
	307. STAND, 180° RIGHT TURN, STAND (B) The Handler stops and the dog stands beside the Handler. Together the team does a tight 180° turn to the right on the spot, stops and the dog is directed to a stand position. The dog remains standing until the team moves forward.
	308. STAND, 180° LEFT TURN, STAND (B) The Handler stops and the dog stands beside the Handler. Together the team does a tight 180° turn to the left on the spot, stops and the dog is directed to a stand position. The dog remains standing until the team moves forward.
	309. STAND, CIRCLE AROUND HANDLER, STAND (A) (Was KUSA 308) The Handler stops and the dog stands beside the Handler. After that the Handler directs the dog to circle forward around the Handler. Thereafter the dog resumes a stand at the Handler's side. The dog remains standing until the team moves forward. Static exercise
	310. TURN TOWARD (B) (Was KUSA 314) While moving, the team does a tight and simultaneous 180° turn toward each other and continues in the opposite direction. The heeling side is changed.
	311. SIDE SHIFT BEHIND (A) (Was KUSA 315) While moving, the dog makes a side shift behind the Handler. The dog is not allowed to spin to make the shift. The heeling side is changed.
	312. SIDE SHIFT BETWEEN LEGS (A) (Was KUSA 316) The dog makes a side shift between the Handler's legs. The Handler may stop when the dog performs the exercise. The Handler is allowed to lift a leg to make the side shift fluently. The heeling side is changed.
	313. BOTH ABOUT TURN RIGHT (B) (Was KUSA 318) While moving, both Handler and the dog do a tight and simultaneous 180° turn to the right and continue in the opposite direction. The heeling side is changed.
	314. BOTH ABOUT TURN LEFT (B) (Was KUSA 317) While moving, both Handler and the dog do a tight and simultaneous 180° turn to the left and continue in the opposite direction. The heeling side is changed.

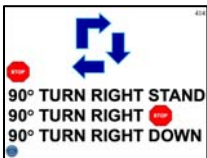
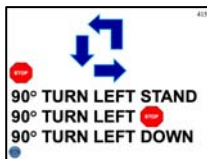
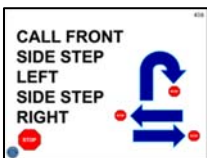
	315. STOP, SIDE SHIFT BEHIND, STOP (A) (Was KUSA 319) The Handler stops and the dog sits beside the Handler. After that the dog is directed to make a side shift behind the Handler and to resume a sit on the other side. The dog is not allowed to spin to make the shift. When completed, the team moves forward. The heeling side is changed.
	316. STOP, SIDE SHIFT IN FRONT, STOP (A) (Was KUSA 320) The Handler stops and the dog sits beside the Handler. After that the dog is directed to make a side shift in front of the Handler and to resume a sit on the other side. The dog must spin to make the shift. When completed, the team moves forward. The heeling side is changed.
	317. MOVING STAND, WALK AROUND (A) (Was KUSA 321) While moving, the dog is directed to a stand position and the Handler, without pausing, walks forward, then around the dog, back to the side of the dog and makes a stop. The dog remains standing until the team moves forward.
	318. MOVING DOWN, WALK AROUND (A) (Was KUSA 322) While moving, the dog is directed to a down position and the Handler, without pausing, walks forward, then around the dog, back to the side of the dog and makes a stop. The dog stays down until the team moves forward.
	319. STOP, STAND, WALK FORWARD (A) (Was KUSA 324) The Handler stops and the dog sits beside the Handler. After that the dog is directed to a stand position. Thereafter the Handler, without the dog, walks forward either to the recall cone (C) and recalls the dog (no change of the heeling side) or to the recall sign and follows the instructions on the recall sign. If no additional recall sign is placed, the recall cone and the recall itself are part of this exercise.
	320. SEND OVER TWO JUMPS (D) (Was KUSA 326) The dog is sent over two jumps at the earliest next to the sign that is two metres before the first jump. The jumps can be in a straight line or in an angle up to 90°, but they must be at minimum 4 m apart from each other. The 4m is measured from the middle of the horizontal bars. At the same time the Handler continues alongside the jumps.
 (SPECIAL RECALL SIGN)	321. TURN AROUND, RECALL (B) This sign can only be used after exercises 319, 408 and 409, instead of a recall cone, and must be placed 3 to 5 m from the previous sign. The Handler turns around, stops, and recalls the dog. The Handler may stop before turning around. The dog is directed to go to the left heel position (without a sit). When reached, the team moves forward. Return to left handling.

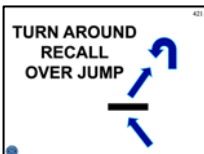
 (SPECIAL RECALL SIGN)	322. TURN AROUND, RECALL FRONT STOP, RIGHT TO LEFT, STOP (B) This sign can only be used after exercises 319, 408 and 409, instead of a recall cone, and must be placed 3 to 5 m from the previous sign. The Handler turns around, stops, and recalls the dog. The Handler may stop before turning around. The dog is directed to sit in front of the Handler. The dog is then directed to move to the Handler's right and behind the Handler to the left side. The dog sits before the team moves forward. Return to left handling.
 (SPECIAL RECALL SIGN)	323. TURN AROUND, RECALL FRONT STOP, LEFT TO LEFT, STOP (B) This sign can only be used after exercises 319, 408 and 409, instead of a recall cone, and must be placed 3 to 5 m from the previous sign. The Handler turns around, stops, and recalls the dog. The Handler may stop before turning around. The dog is directed to sit in front of the Handler. The dog then is directed to move directly to the Handler's left side. The dog sits before the team moves forward. Return to left handling.
	324. SPIN APART WHEN MOVING (A) (Was KUSA 313) While the team is moving, the dog spins a circle forward and simultaneously the Handler spins in the opposite direction also moving forward.

LEVEL 4 signs

SIGN	DESCRIPTION
	401. 2 SIDE STEPS RIGHT (B) While moving, the Handler takes two steps to the right and the dog follows simultaneously aligned with and parallel to the Handler. The team continues to the right side of the sign.
	402. 2 SIDE STEPS LEFT (B) While moving, the Handler takes two steps to the left and the dog follows simultaneously aligned with and parallel to the Handler.
	403. STOP, 2 SIDE STEPS RIGHT, STOP (B) The Handler stops and the dog sits beside the Handler. The Handler takes two steps to the right and stops. The dog moves simultaneously aligned with and parallel to the Handler and resumes a sit when the Handler stops. The team continues on the right side of the sign.
	404. STOP, 2 SIDE STEPS LEFT, STOP (B) The Handler stops and the dog sits beside the Handler. The Handler takes two steps to the left and stops. The dog moves simultaneously aligned with and parallel to the Handler and resumes a sit when the Handler stops.
	405. TURN APART (B) (Was KUSA 404) While moving, the team does a tight and simultaneous 180° turn away from each other and continues in the opposite direction. The heeling side is changed.
	406. SIDE SHIFT IN FRONT (A) (Was KUSA 405) While moving, the dog makes a side shift in front of the Handler. The dog is not allowed to spin to make the shift. The heeling side is changed.
	407. CIRCLE AROUND HANDLER (A) (Was KUSA 406) While the team is moving, the dog circles forward around the Handler and returns to the initial heel position.
	408. MOVING SIT, WALK FORWARD (A) (Was KUSA 407) While moving, the dog is directed to a sit position and the Handler, without pausing and without the dog, walks forward either to the recall cone (C) and recalls the dog (no change of the heeling side) or to a recall sign and follows the instructions on the recall sign. If no additional recall sign is placed, the recall cone and the recall itself are part of this exercise.

	409. MOVING DOWN, WALK FORWARD (A) (Was KUSA 323) While moving, the dog is directed to a down position and the Handler, without pausing and without the dog, walks forward either to the recall cone (C) and recalls the dog (no change of the heeling side) or to a recall sign and follows the instructions on the recall sign. If no additional recall sign is placed, the recall cone and the recall itself are part of this exercise.
	410. STOP, SEND AWAY, STAND, WALK FORWARD, RECALL (Was KUSA 408) The Handler stops and the dog sits beside the Handler. The team is allowed to turn towards the cone when stopping. The cone is placed 3 to 5 m away in an angle up to 90° to the left or the right. The Handler then sends the dog to a stand next to the cone (at least one paw must be within one metre of the cone). The dog remains standing at the cone while the Handler walks forward to the recall cone (C) and recalls the dog (no change of the heeling side). The recall cone and the recall itself are part of this exercise. There must be at least 2 m between the cone and the recall cone.
	411. CALL FRONT STAND, BACK AWAY, STAND, WALK FORWARD, RECALL (Was KUSA 409) The Handler stops and the dog is directed to stand in front of the Handler. The dog is then directed to back away at least three dog lengths from the Handler to a stand. While the dog remains standing, the Handler walks forward next to the dog and then recalls the dog, without pausing, returning to left handling.
	412. 3 STEPS BACKWARDS (Was KUSA 410) While moving, the Handler takes at least three steps backwards. The dog moves simultaneously aligned with and parallel to the Handler. When completed, the team moves forward.
	413. STOP, 1 STEP BACK STAND, 2 STEPS BACK STOP, 3 STEPS BACK DOWN The Handler stops, and the dog sits beside the Handler. After that the Handler takes one step backwards and stops. The dog moves simultaneously aligned with and parallel to the Handler and assumes a stand when the Handler stops. Then the Handler takes two steps backwards and stops. The dog moves simultaneously aligned with and parallel to the Handler and assumes a sit when the Handler stops. Thereafter the Handler takes three steps backwards and stops. The dog moves simultaneously aligned with and parallel to the Handler and assumes a down when the Handler stops. The dog stays down until the team moves forward.

 90° TURN RIGHT STAND 90° TURN RIGHT 90° TURN RIGHT DOWN	414. STOP, 90° RIGHT TURN STAND, 90° RIGHT TURN STOP, 90° RIGHT TURN DOWN (B) The Handler stops and the dog sits beside the Handler. After that the Handler does a 90° turn to the right on the spot and stops. The dog moves simultaneously with the Handler and assumes a stand when the Handler stops. The Handler then does again a 90° turn to the right on the spot and stops. The dog moves simultaneously with the Handler and assumes a sit when the Handler stops. Thereafter the Handler does again a 90° turn to the right on the spot and stops. The dog moves simultaneously with the Handler and assumes a down when the Handler stops. The dog stays down until the team moves forward. The new direction is 90° left to the original one.
 90° TURN LEFT STAND 90° TURN LEFT 90° TURN LEFT DOWN	415. STOP, 90° LEFT TURN STAND, 90° LEFT TURN STOP, 90° LEFT TURN DOWN (B) The Handler stops and the dog sits beside the Handler. After that the Handler does a 90° turn to the left on the spot and stops. The dog moves simultaneously with the Handler and assumes a stand when the Handler stops. The Handler then does again a 90° turn to the left on the spot and stops. The dog moves simultaneously with the Handler and assumes a sit when the Handler stops. Thereafter the Handler does again a 90° turn to the left on the spot and stops. The dog moves simultaneously with the Handler and assumes a down when the Handler stops. The dog stays down until the team moves forward. The new direction is 90° right to the original one.
 CALL FRONT SIDE STEP LEFT SIDE STEP RIGHT	416. CALL FRONT STOP, SIDESTEP LEFT STOP, SIDESTEP RIGHT STOP (A) The Handler stops and the dog is directed to sit in front of the Handler. After that the Handler takes one side step to the left and stops. The dog moves simultaneously aligned with and parallel to the Handler and resumes a sit in front of the Handler when the Handler stops. Thereafter the Handler takes one side step to the right and stops. The dog moves simultaneously aligned with and parallel to the Handler and resumes a sit in front of the Handler when the Handler stops. The dog is then directed to the Handler's left side and resumes a sit beside the Handler. The dog remains sitting until the team moves forward. Return to left handling.
 90° TURN LEFT AROUND CONE	417. 90° LEFT TURN AROUND CONE (A) This exercise can only be set up, when the dog is in the beginning of the exercise on the Handler's left side (left handling). While moving, before reaching the sign, the Handler sends the dog around the cone, which is 1 to 2 m away from the back of the sign. The dog must clearly have started its approach to the cone before the Handler reaches the sign. The dog circles the cone clockwise while the Handler turns 90° left before reaching the cone. The Handler can slow down while the dog is going around the cone. The exercise ends with the dog returning to the Handler's right side. The heeling side is changed. Return to right handling.

	418. 90° RIGHT TURN AROUND CONE (A) This exercise can only be set up, when the dog is in the beginning of the exercise on the Handler's right side (right handling). While moving, before reaching the sign, the Handler sends the dog around the cone, which is 1 to 2 m away from the back of the sign. The dog must clearly have started its approach to the cone before the Handler reaches the sign. The dog circles the cone counter clockwise while the Handler turns 90° right before reaching the cone. The Handler can slow down while the dog is going around the cone. The exercise ends with the dog returning to the Handler's left side. The heeling side is changed. Return to left handling.
	419. MOVING SIT, WALK AROUND (A) While moving, the dog is directed to a sit position and the Handler, without pausing, walks forward, then around the dog, back to the side of the dog and makes a stop. The dog remains sitting until the team moves forward.
	420. STOP, RECALL OVER JUMP (A) (Was KUSA 412) The Handler stops next to the sign that is two metres before the jump and the dog sits beside the Handler. After that the Handler walks forward, without the dog, and recalls the dog after having passed the jump. The dog does the jump and returns to the initial heel side (no change of the heeling side). The Handler may reduce the pace to catch up with the dog.
 SPECIAL RECALL SIGN	421. TURN AROUND, RECALL OVER JUMP WITH DIRECTIONS (B) This sign can only be used after exercises 319, 408 and 409, instead of a recall cone and must be placed 8 m from the previous sign. A jump is placed exactly halfway between this sign and the previous one, so that the nearest side of the jump is 2 m off-centre to either left or right. The Handler turns around, stops, and recalls the dog over the jump to the left heel position (without a sit). The Handler may stop before turning around. The team then moves forward. Return to left handling.
 SPECIAL RECALL SIGN	422. TURN AROUND, BACK AWAY, SIT, DOWN, RECALL (B) This sign can only be used after exercises 319, 408 and 409, instead of a recall cone, and must be placed 3 to 5 m from the previous sign. The Handler turns around, stops, and directs the dog to back away at least one dog length. The Handler may stop before turning around. After that the dog is directed to a sit and then to a down position. Thereafter the dog is recalled to the Handler's left side. The dog sits before the team moves forward. Return to left handling.